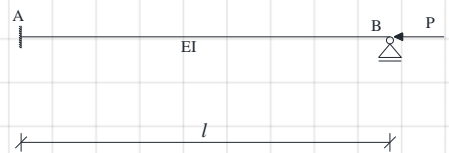
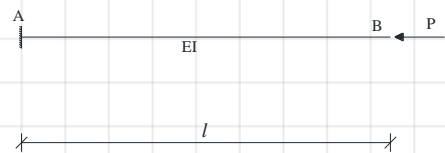
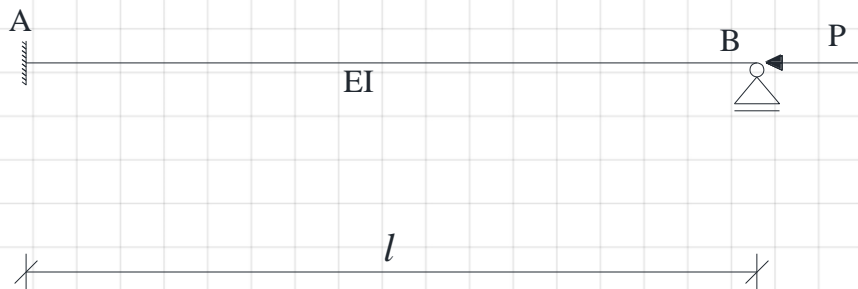


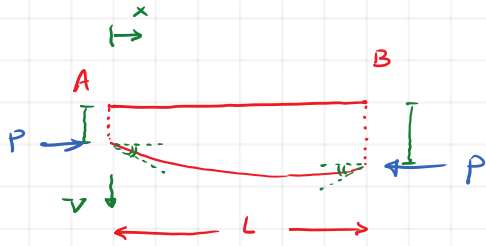
In the stability analysis there are different definitions for boundary conditions. Essential boundary conditions also known as kinematic boundary conditions, neutral boundary conditions and equilibrium boundary conditions. In the general form, determine the general essential, neutral and equilibrium boundary conditions.

Then, write each boundary condition for different beam conditions based on their categories.



For the beam shown below, determine the first buckling load.





$$\pi = \frac{1}{2} \int_0^L EI k^2 dx - \frac{P}{2} \int_0^L v'^2 dx$$

$$k = -\frac{v''}{\sqrt{1-v'^2}} = -v'' \cdot \left(1 + \frac{1}{2}v'^2\right) \approx -v''$$

$$\pi = \frac{1}{2} \int_0^L EI v''^2 dx - \frac{P}{2} \int_0^L v'^2 dx$$

$$\delta \pi = \frac{1}{2} \int_0^L E \cdot I \cdot 2v'' \cdot \delta(v'') dx - \frac{P}{2} \int_0^L 2v' \cdot \delta v' dx$$

$$\int_0^L \underbrace{E \cdot I \cdot v''}_{u} \cdot \underbrace{\delta(v'')}_{dv} dx \Rightarrow \textcircled{1}$$

$$du = (EI v'')' \quad v = \delta v'$$

$$\textcircled{1} = EI v'' \cdot \delta v' - \int_0^L \underbrace{(EI v'')'}_u \cdot \underbrace{\delta v'}_{dv} dx$$

$$du = (EI v'')', \quad v = \delta v'$$

$$\textcircled{2} = (EI v'')' \cdot \delta v - \int_0^L (EI v'')' \cdot \delta v \cdot dx$$

$$\int u \cdot dv = u \cdot v - \int v \cdot du$$

$$\textcircled{3} \Rightarrow P \int_0^L \underbrace{v'}_u \cdot \underbrace{\delta v'}_{dv} \cdot dx$$

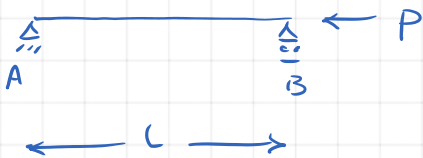
$$du = (v')', \quad v = \delta v$$

$$\textcircled{3} = P \left[ v' \cdot \delta v - \int_0^L (v')' \cdot \delta v \cdot dx \right]$$

$$\delta \Pi = \int_0^L EI v'' \cdot \delta v' - \int_0^L (EI v'')' \cdot \delta v + \int_0^L (EI v'')'' \cdot \delta v \cdot dx - P \cdot v' \cdot \delta v + \int_0^L P(v')' \cdot \delta v \cdot dx$$

$$\delta \Pi = \int_0^L EI v'' \cdot \delta v' - \int_0^L ((EI v'')' + P v') \delta v + \int_0^L ((EI v'')'' + (P v')') \delta v \cdot dx$$

$$EI v''(L) \cdot \delta v'(L) - \left[ ((EI v'')'(L) + P v'(L)) \delta v(L) \right] + \int_0^L (EI v'' + P v'') \delta v \cdot dx - EI v''(0) \cdot \delta v'(0) - \left[ -((EI v'')'(0) + P v'(0)) \delta v(0) \right] \quad \textcircled{I}$$



$$\begin{cases} EI v'' = -M \\ (EI v'')' = -Q \end{cases}$$

$$\textcircled{I} \quad -M(L) \cdot \delta v'(L) - \left[ (-Q(L) + P v'(L)) \delta v(L) \right] + \int_0^L (EI v'' + P v'') \delta v \cdot dx + M(0) \cdot \delta v'(0) - \left[ -(-Q(0) + P v'(0)) \delta v(0) \right]$$

$$\begin{cases} M(L) = 0 \\ M(0) = 0 \end{cases}$$

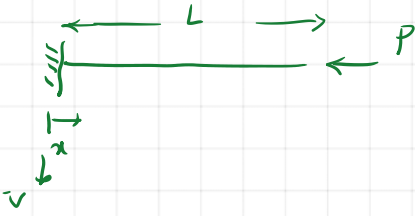
Neutral B.C

$$\begin{cases} \delta v(L) = 0 \\ \delta v(0) = 0 \end{cases}$$

essential B.C

$$EI v'' + P v'' = 0$$

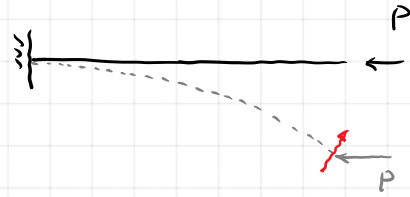
Equilibrium B.C



$$\textcircled{I} \quad -M(L) \cdot \delta v'(L) - \left[ (-Q(L) + P v'(L)) \delta v(L) \right] + \int_0^L (EI v'''' + P v''') \delta v \cdot dx$$

$x=0 \Rightarrow \delta v(0) = 0$   
 $x=0 \Rightarrow \delta v'(0) = 0$

$M(L) = 0$   
 $Q(L) - P v'(L) = 0$



$EI v'''' + P v''' = 0 \rightarrow \text{Equilibrium B.C}$



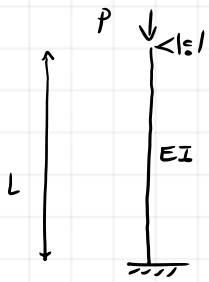
$$\textcircled{I} \quad -M(L) \cdot \delta v'(L) - \left[ (-Q(L) + P v'(L)) \delta v(L) \right] + \int_0^L (EI v'''' + P v''') \delta v \cdot dx$$

$\delta v(0) = 0$      $\delta v'(0) = 0$      $\delta v(L) = 0$      $\delta v'(L) \neq 0 \Rightarrow M(L) = 0$



$$\textcircled{I} \quad -M(L) \cdot \delta v'(L) - \left[ (-Q(L) + P v'(L)) \delta v(L) \right] + \int_0^L (EI v'''' + P v''') \delta v \cdot dx$$

$\delta v(0) = 0$      $\delta v'(0) = 0$      $\delta v'(L) = 0$      $\delta v(L) \neq 0 \Rightarrow -Q(L) + P v'(L) = 0$



$$EI v^{(4)} + P v'' = 0$$

$$v(0) = 0$$

$$v'(0) = 0$$

$$\uparrow x \quad v(L) = 0, \quad M(L) = 0 \Rightarrow EI v''(L) = 0$$

$$v^{(4)} + \frac{P}{EI} v'' = 0$$

$$\frac{P}{EI} = \lambda^2$$

$$v^{(4)} + \lambda^2 v'' = 0 \Rightarrow r^4 + \lambda^2 r^2 = 0 \Rightarrow$$

$$r^2 [r^2 + \lambda^2] = 0 \rightarrow \begin{cases} r = 0 \\ r = 0 \\ r = \pm \lambda i \end{cases}$$

$$v_h = A \sin \lambda x + B \cos \lambda x + \cancel{e^{\lambda x}} (C x + D)$$

$$v = A \sin \lambda x + B \cos \lambda x + C x + D$$

$$v' = A \lambda \cos \lambda x - B \lambda \sin \lambda x + C$$

$$v'' = -A \lambda^2 \sin \lambda x - B \lambda^2 \cos \lambda x$$

$$v(0) = 0 \Rightarrow B + D = 0$$

$$v'(0) = 0 \Rightarrow A \lambda + C = 0$$

$$v(L) = 0 \Rightarrow A \sin \lambda L + B \cos \lambda L + C L + D = 0$$

$$v''(L) = 0 \Rightarrow -A \lambda^2 \sin \lambda L - B \lambda^2 \cos \lambda L = 0$$

$$\begin{bmatrix} A & B & C & D \\ 0 & 1 & 0 & 1 \\ \lambda & 0 & 1 & 0 \\ \sin \lambda L & \cos \lambda L & L & 1 \\ \sin \lambda L & \cos \lambda L & 0 & 0 \end{bmatrix} = T$$

$$\det(T) = 0$$

$$T(l, \lambda) := \begin{bmatrix} 0 & 1 & 0 & 1 \\ \lambda & 0 & 1 & 0 \\ \sin(\lambda \cdot l) & \cos(\lambda \cdot l) & l & 1 \\ \sin(\lambda \cdot l) & \cos(\lambda \cdot l) & 0 & 0 \end{bmatrix}$$

$$\lambda L \cos \lambda L - \sin \lambda L = 0$$

$$\det(T(l, \lambda)) \rightarrow -\sin(\lambda \cdot l) + \lambda \cdot l \cdot \cos(\lambda \cdot l)$$

$$\lambda \cdot L \cos \lambda L - \sin \lambda L = 0 \Rightarrow \lambda L = \tan \lambda L$$

$$\rightarrow \boxed{\lambda L - \tan \lambda L = 0}$$

$$(\lambda L)_1 = 4.493 \Rightarrow \lambda^2 L^2 = 4.493^2 = 20.187$$

$$(\lambda L)_2 = 7.725$$

$$\frac{P_{cr,1}}{EI} \cdot L^2 = 20.187 \Rightarrow P_{cr,1} = 20.187 \frac{EI}{L^2}$$

$$P_{cr,1} = \frac{\pi^2 \cdot EI}{L^2} \cdot \frac{20.187}{\pi^2} = \frac{\pi^2 EI}{L^2 \cdot \frac{\pi^2}{20.187}} = \frac{\pi^2 EI}{0.49 L^2} = \frac{\pi^2 EI}{(0.7L)^2}$$

$$\boxed{L_{eff} = 0.7L}$$