

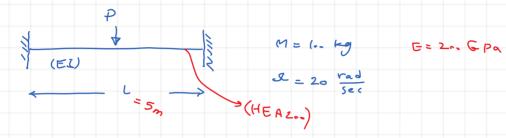
In the previous <u>video</u>, we analyzed the response of a system under harmonic loading, ignoring the effect of damping. In this video, we will delve deeper into the topic by solving a practical example that will allow us to explore the impact of various factors, including the loading frequency, on the system's response. By examining these factors, we will better understand how the system behaves under different conditions and how we can optimize its performance.

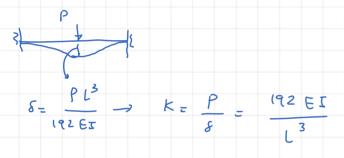


SHI

transient Vibration

Steady Vibration





 $E := 200 \ GPa \qquad I := 36.92 \cdot 10^6 \cdot mm^4 \qquad M := 100 \ kg \qquad l := 5 \ m \qquad \Omega := 20 \ \frac{rad}{s}$ $k := \frac{192 \cdot E \cdot I}{l^3} = \left(1.134 \cdot 10^4\right) \frac{kN}{m} \qquad w := \sqrt{\frac{k}{M}} = 336.776 \frac{rad}{s} \qquad T := \frac{2 \cdot \pi}{w} = 0.019 \ s \qquad f := \frac{1}{T} = 53.6 \ Hz$ $\beta := \frac{\Omega}{w} = 0.059 \qquad p_0 := M \cdot g \qquad u_0 := 0 \ mm \qquad u'_0 := 0 \ \frac{mm}{s}$

$$u(t) := u_0 \cdot \cos(w \cdot t) + \begin{pmatrix} u'_0 & p_0 \\ w & k \end{pmatrix} \cdot \frac{\beta}{1 - \beta^2} \cdot \sin(w \cdot t) + \frac{p_0}{k} \cdot \frac{1}{1 - \beta^2} \cdot \sin(\Omega \cdot t)$$

$$t := 0,0.001 \ s... 2 \ s$$

$$t := 0,0.001 \ s... 2 \ s$$

$$0.001 \ s... 2 \ s$$

$$0.002 \ s... 3 \ s$$

$$0.003 \ s... 3 \ s$$

$$0.004 \ s... 3 \ s$$

$$0.005 \ s... 3 \ s$$

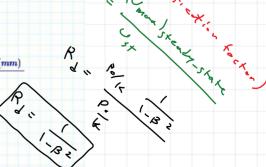
$$0.006 \ s... 3 \ s$$

$$0.007 \ s... 3 \ s$$

$$0.008 \ s... 3 \ s$$

$$0.009 \ s$$

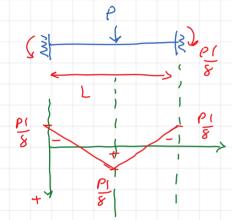
Johnson L. March J. S. K. C. K



SH

$$\frac{U}{S7} = \frac{P_{c}}{K} = \frac{981 \text{ N}}{1.139 \times 1.6} = 0.086 \text{ mm}$$

$$R_{J} = \frac{1}{1-\beta^{2}} = 10035$$



$$M = \frac{P1}{8} = 613 N m$$

Max imum

Beding moment

for the cutine

harmonic laad

being applied

613 x 0 = 711 1.19 N.m

